CALL FOR PAPERS

ICRCV 2025

2025 7th International Conference on Robotics and Computer Vision

October 24-26, 2025 / Hong Kong

2025 7th International Conference on Robotics and Computer Vision (ICRCV 2025) will be held in Hong Kong during October 24-26, 2025. In addition to keynote and invited speeches, the conference will feature oral presentations and poster sessions, providing a comprehensive platform for the exchange and display of the latest research findings. As an international metropolis, Hong Kong not only boasts rich scientific and technological resources but also offers a unique blend of cultural charm and stunning natural landscapes. We look forward to your active participation and to an inspiring and enriching experience at ICRCV 2025!

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SUBMISSION

★A. Full Paper (for Presentation and Publication)
★B. Abstract (Presentation only)

Online Submission System: http://www.zmeeting.org/submission/icrcv2025
Full Paper Template: https://www.icrcv.org/template.docx
LaTex Template: https://www.icrcv.org/Conference-LaTeX-template.zip
Abstract Template: https://www.icrcv.org/abstract.docx

Important Dates
Submission Deadline: July 15th, 2025
Notification Day: August 15th, 2025
Registration Deadline: August 30th, 2025

PUBLICATION

IEEE

Accepted full papers will be published in ICRCV 2025 Conference Proceedings. The proceedings will be archived in IEEE Xplore and indexed by Ei Compendex and Scopus.

*ICRCV 2021-2024 conference proceedings have been archived in IEEE Xplore and indexed by Ei Compendex and Scopus.

TOPICS

Topics of interest for submission include, but are not limited to:

Track I: Robot Design and Control
Mechanism design and applications
Micro robots and micro-manipulation
Mobile robotics
Mobile sensor networks

Track II: Intelligent Control
Adaptive control
Complex systems
Control applications
Control of biological systems

Track III: Artificial Intelligence in Robot Systems
Artificial intelligence
Evolutionary computation
Fuzzy and neural systems
Human-centered systems

Track IV: Machine Vision and Visualization
Activity/behavior recognition
Autonomous driving
Biomedical Image analysis
Computational imaging

Track V: Robotics in Biomedicine and Rehabilitation
Applications for robotics in medicine
Assist-as-needed exoskeleton robots
Biomechatronics
Medical robots and bio-robotics

More details: http://www.icrcv.org/cfp.html